

Discrete-time Dynamic Optimization

Consider the problem:

$$\text{Max}_{u_t} \sum_{t=0}^T \beta^t r(x_t, u_t) = r(x_0, u_0) + \beta r(x_1, u_1) + \dots + \beta^T r(x_T, u_T)$$

subject to: $x_{t+1} = g(x_t, u_t)$, x_0 given.

x_t : state variable.

u_t : control variable

β^t : discount factor

$r(x_t, u_t)$: single-period reward function

$g(x_t, u_t)$: state transition function

Classical Optimization Techniques

Example: The Ramsey Problem

$$\text{Max}_{c_t} \sum_{t=0}^T \beta^t u(c_t)$$

subject to: $k_{t+1} = f(k_t) - c_t$ and $k_{T+1} \geq 0$

Form the Lagrangian:

$$\mathcal{L} = u(c_0) + \dots + \beta^t u(c_t) + \beta^{t+1} u(c_{t+1}) + \dots + \beta^T u(c_T) \\ + \lambda_0 [f(k_0) - c_0 - k_1] + \dots + \lambda_t [f(k_t) - c_t - k_{t+1}] + \lambda_T k_{T+1}$$

First-order conditions include:

$$\frac{\partial \mathcal{L}}{\partial c_t} = \beta^t \frac{\partial u}{\partial c_t} - \lambda_t = 0 \\ \frac{\partial \mathcal{L}}{\partial c_{t+1}} = \beta^{t+1} \frac{\partial u}{\partial c_{t+1}} - \lambda_{t+1} = 0 \\ \frac{\partial \mathcal{L}}{\partial k_{t+1}} = -\lambda_t + \lambda_{t+1} f'(k_{t+1}) = 0 \\ \lambda_T \geq 0, \quad k_{T+1} \geq 0, \quad \lambda_T k_{T+1} = 0$$

Sustituting for the λ terms, we obtain:

$$1 = \beta \frac{u'(c_{t+1})}{u'(c_t)} f'(k_{t+1})$$

Euler Equation: difference equation system in c_t, k_t

Initial condition: k_0 .

Final value condition: $k_{T+1} = 0$

Infinite Horizon Case

Now suppose that $T \rightarrow +\infty$

If a steady-state exists, then $c_{t+1} = c_t$, and so:

$$\begin{aligned}\lim_{t \rightarrow \infty} k(t) &= \bar{k} \\ \lim_{t \rightarrow \infty} c(t) &= \bar{c} = f(\bar{k}) \\ \beta f'(\bar{k}) &= 1\end{aligned}$$

Backwards Induction with Finite Horizon

In the finite-horizon problem, we may try another approach.

Problem:

$$\text{Max}_{c_t} \sum_{t=0}^T \beta^t \ln(c_t)$$

$$\text{subject to: } k_{t+1} = k_t^\alpha - c_t \text{ and } k_{T+1} \geq 0$$

Suppose we start by solving the problem at time T .

$$\text{Max}_{c_T} \ln(c_T)$$

$$\text{subject to: } k_{T+1} = k_T^\alpha - c_T \geq 0$$

First we trivially obtain: $c_T^* = k_T^\alpha$.

Question: What is the value of setting $c_T^* = k_T^\alpha$?

Denote this value as $V_0 = \ln(k_T^\alpha) = \alpha \ln k_T$

The zero subscript indicates zero remaining periods.

Next we pose:

$$\text{Max}_{c_{T-1}} [\ln c_{T-1} + \beta V_0], \text{ subject to: } k_T = k_{T-1}^\alpha - c_{T-1}$$

$$\text{or: } \text{Max}_{c_{T-1}} [\ln c_{T-1} + \beta \alpha \ln k_T], \text{ subject to: } k_T = k_{T-1}^\alpha - c_{T-1}$$

$$\text{or: } \text{Max}_{c_{T-1}} [\ln c_{T-1} + \beta \alpha \ln(k_{T-1}^\alpha - c_{T-1})]$$

Proceed as:

$$\frac{d[\ln c_{T-1} + \beta \alpha \ln(k_{T-1}^\alpha - c_{T-1})]}{dc_{T-1}} = 0$$

$$\frac{1}{c_{T-1}} - \frac{\alpha \beta}{k_{T-1}^\alpha - c_{T-1}} = 0$$

$$k_{T-1}^\alpha - c_{T-1} = \alpha \beta c_{T-1}$$

$$c_{T-1}^* = \frac{k_{T-1}^\alpha}{(1 + \alpha \beta)}$$

$$\begin{aligned}
k_T^* &= k_{T-1}^\alpha - c_{T-1}^* \\
&= k_{T-1}^\alpha - \frac{k_{T-1}^\alpha}{(1 + \alpha\beta)} \\
&= \left[1 - \frac{1}{1 + \alpha\beta} \right] k_{T-1}^\alpha \\
&= \frac{\alpha\beta}{1 + \alpha\beta} k_{T-1}^\alpha
\end{aligned}$$

We now derive V_1 :

$$\begin{aligned}
V_1 &= \ln c_{T-1}^* + \alpha\beta \ln k_T^* \\
&= \ln \left(\frac{k_{T-1}^\alpha}{(1 + \alpha\beta)} \right) + \alpha\beta \ln \left(\frac{\alpha\beta}{1 + \alpha\beta} k_{T-1}^\alpha \right) \\
&= \alpha \ln k_{T-1} - \ln(1 + \alpha\beta) + \alpha\beta \ln \left(\frac{\alpha\beta}{1 + \alpha\beta} \right) + \alpha^2 \beta \ln k_{T-1}
\end{aligned}$$

Simplifying:

$$V_1 = \alpha(1 + \alpha\beta) \ln k_{T-1} - \ln(1 + \alpha\beta) + \alpha\beta \ln \left(\frac{\alpha\beta}{(1 + \alpha\beta)} \right)$$

This is of the form:

$$V_1 = \alpha(1 + \alpha\beta) \ln k_{T-1} + \Omega_{T-1}$$

Next we pose:

$$\text{Max}_{c_{T-2}} [\ln c_{T-2} + \beta V_1], \text{ subject to: } k_{T-1} = k_{T-2}^\alpha - c_{T-2}$$

Rewrite as:

$$\text{Max}_{c_{T-2}} [\ln c_{T-2} + \beta(\alpha(1 + \alpha\beta) \ln(k_{T-2}^\alpha - c_{T-2}) + \Omega_{T-1})]$$

First-order Condition:

$$\frac{d[\quad]}{dc_{T-2}} = \frac{1}{c_{T-2}} - \frac{\alpha\beta(1 + \alpha\beta)}{k_{T-2}^\alpha - c_{T-2}} = 0$$

Solution is of the form:

$$\begin{aligned}
c_{T-2}^* &= \frac{k_{T-2}^\alpha}{(1 + \alpha\beta + (\alpha\beta)^2)} \\
k_{T-1}^* &= \frac{\alpha\beta + (\alpha\beta)^2}{(1 + \alpha\beta + (\alpha\beta)^2)} k_{T-2}^\alpha
\end{aligned}$$

Next:

$$\begin{aligned}
V_2 &= \ln c_{T-2}^* + \beta V_1 \\
&= \ln c_{T-2}^* + \beta[\alpha(1 + \alpha\beta) \ln k_{T-1}^* + \Omega_{T-1}]
\end{aligned}$$

Collecting terms, we find that:

$$V_2 = \alpha(1 + \alpha\beta + (\alpha\beta)^2) \ln k_{T-2} + \Omega_{T-2}$$

A pattern is emerging in which:

$$V_{T-t} = \left(\alpha \sum_{i=0}^{T-t} (\alpha\beta)^i \right) \ln k_t + \Omega_{T-t}$$

$$c_t^* = \frac{k_t^\alpha}{\sum_{i=0}^{T-t} (\alpha\beta)^i}$$

We have solved for a series of policy functions, c_t^* .

As a byproduct, we have also solved for a series of value functions, V_{T-t} .

Now consider the infinite horizon problem:

$$\text{Max}_{c_t} \sum_{t=0}^{\infty} \beta^t u(c_t)$$

$$\text{subject to: } k_{t+1} = f(k_t) - c_t \text{ and } \lim_{t \rightarrow +\infty} k_t \geq 0$$

We conjecture that the solution is given by:

$$c_t^* = \lim_{t \rightarrow +\infty} \frac{k_t^\alpha}{\sum_{i=0}^{T-t} (\alpha\beta)^i} = (1 - \alpha\beta)k_t^\alpha$$

$$V = \lim_{t \rightarrow +\infty} \left(\alpha \sum_{i=0}^{T-t} (\alpha\beta)^i + \Omega_{T-t} \right)$$

$$= \frac{\alpha}{(1 - \alpha\beta)} \ln k_t + \text{constant}$$

Infinite Horizon Problems: A Recursive Approach

$$\text{Max}_{u_t} \sum_{t=0}^{\infty} \beta^t r(x_t, u_t)$$

$$\text{subject to: } x_{t+1} = g(x_t, u_t), x_0 \text{ given.}$$

The objective may also be written out as:

$$\text{Max}_{u_t} [r(x_0, u_0) + \beta r(x_1, u_1) + \beta^2 r(x_2, u_2) + \dots]$$

Next consider the problem:

$$\text{Max}_{u_t} [r(x_1, u_1) + \beta r(x_2, u_2) + \beta^2 r(x_3, u_3) + \dots]$$

subject to: $x_{t+1} = g(x_t, u_t)$, x_1 given.

Now suppose that we know the solution to the second problem.

Solution consists of $\{u_1^*, u_2^*, \dots, x_2^*, x_3^*, \dots\}$.

Now define:

$$V(x_1) = [r(x_1, u_1^*) + \beta r(x_2^*, u_2^*) + \beta^2 r(x_3^*, u_3^*) + \dots]$$

Conjecture that $V(\cdot)$ is time-invariant.

Next return to the original problem:

$$\underset{u_t}{Max} [r(x_0, u_0) + \beta r(x_1, u_1) + \beta^2 r(x_2, u_2) + \dots]$$

This problem is characterized by time-consistency.

We can reoptimize at any time.

The remaining solution is unchanged.

The problem can be restated as:

$$\begin{aligned} &\underset{u_0}{Max} [r(x_0, u_0) + \beta r(x_1, u_1^*|x_1) + \beta^2 r(x_2^*|x_1, u_2^*|x_1) + \dots] \\ &= \underset{u_0}{Max} [r(x_0, u_0) + \beta V(x_1)] \text{ where } x_1 = g(x_0, u_0) \end{aligned}$$

Define the function, $h(x_0)$, as the solution, $u^*(x_0)$.

The functions V and h are related through the Bellman equation:

$$\begin{aligned} V(x) &= \max_u \{r(x, u) + \beta V[g(x, u)]\} \\ &= \max_u \{r(x, u) + \beta V[\tilde{x}]\}, \text{ where } \tilde{x} = g(x, u) \end{aligned}$$

Solving the "max" part of the RHS requires that we set:

$$u = h(x)$$

where $h(x)$ solves the FOC of the maximization problem.

The Bellman equation is a functional equation.

The solution consists of the functions V and h .

For well-behaved problems:

1. Solution consists of a unique concave value function V .
2. Solution for V is the limit as $j \rightarrow \infty$ of:

$$V_{j+1}(x) = \max_u \{r(x, u) + \beta V_j(\tilde{x})\}$$

subject to : $\tilde{x} = g(x, u)$, x given.

3. The time-invariant policy function, $u_t = h(x_t)$, is unique.
4. Off corners, limiting value function is differentiable with:

$$V'(x) = \frac{\partial r}{\partial x}[x, h(x)] + \beta \frac{\partial g[x, u]}{\partial x} V'(\tilde{x})$$

where $\tilde{x} = g[x, h(x)]$

In the Bellman equation, replace u with the optimal value $h(x)$ to obtain:

$$V(x) = r[x, h(x)] + \beta V\{g[x, h(x)]\}$$

Differentiate both sides with respect to x :

$$V'(x) = \frac{\partial r}{\partial x}[x, h(x)] + \frac{\partial r[x, u]}{\partial u} \frac{dh}{dx} + \beta V' \cdot \left(\frac{\partial g[x, u]}{\partial x} + \frac{\partial g[x, u]}{\partial u} \frac{dh}{dx} \right)$$

The terms multiplying $\frac{dh}{dx}$ must be zero by the FOC.

If $\frac{\partial g}{\partial x} = 0$, then we obtain the simpler form:

$$V'(x) = \frac{\partial r}{\partial x}[x, h(x)]$$

Guess and Verify

Must be lucky or faced with standard problem type.

Consider the deterministic Ramsey Problem:

$$\text{Max}_{c_t} \sum_{t=0}^{\infty} \beta^t \ln(c_t)$$

subject to $k_{t+1} = k_t^\alpha - c_t$ and $\lim_{t \rightarrow \infty} k_t \geq 0$

Guess $V(k_t) = \Omega + B \ln k_t$

If correct we need to choose c_t to maximize:

$$\begin{aligned} V(k_t) &= \text{Max}_{c_t} [\ln c_t + \beta(\Omega + B \ln k_{t+1})] \\ &= \text{Max}_{c_t} [\ln c_t + \beta\Omega + \beta B \ln(k_t^\alpha - c_t)] \end{aligned}$$

First-order Condition:

$$\frac{1}{c_t} - \frac{\beta B}{(k_t^\alpha - c_t)} = 0$$

Solving:

$$c_t^* = \frac{k_t^\alpha}{1 + \beta B}$$

Then:

$$\begin{aligned} k_{t+1}^* &= k_t^\alpha - c_t^* = k_t^\alpha - \frac{k_t^\alpha}{1 + \beta B} \\ &= \left(1 - \frac{1}{1 + \beta B} \right) k_t^\alpha \\ &= \left(\frac{\beta B}{1 + \beta B} \right) k_t^\alpha \end{aligned}$$

Now plug into Bellman equation:

$$\begin{aligned} V(k_t) &= \ln c_t^* + \beta\Omega + \beta B \ln(k_{t+1}^*) \\ &= \ln\left(\frac{k_t^\alpha}{1 + \beta B}\right) + \beta\Omega + \beta B \ln\left(\frac{\beta B}{1 + \beta B} k_t^\alpha\right) \\ &= \beta\Omega + \beta B \ln \beta B + (1 + \beta B) \ln\left(\frac{k_t^\alpha}{1 + \beta B}\right) \\ &= \beta\Omega + \beta B \ln \beta B - (1 + \beta B) \ln(1 + \beta B) + (1 + \beta B)\alpha \ln k_t \end{aligned}$$

Therefore:

$$\begin{aligned} B &= \alpha(1 + \beta B) \Rightarrow B = \frac{\alpha}{1 - \alpha\beta} \\ \Omega &= \beta\Omega + \beta B \ln \beta B - (1 + \beta B) \ln(1 + \beta B) \\ \Omega &= \frac{1}{1 - \beta} \left\{ \frac{\alpha\beta}{1 - \alpha\beta} \ln\left(\frac{\alpha\beta}{1 - \alpha\beta}\right) + \frac{\ln(1 - \alpha\beta)}{(1 - \alpha\beta)} \right\} \\ c_t^* &= \frac{k_t^\alpha}{1 + \beta B} = (1 - \alpha\beta)k_t^\alpha \end{aligned}$$

Howard's Policy Improvement Algorithm

This methodology iterates on the h function.

In particular consider the case of a linear h

We generate a sequence, $\{h_0, h_1, \dots\}$

Hope to converge.

Ramsey Example:

$$\text{Max}_{c_t} \sum_{t=0}^{\infty} \beta^t \ln(c_t)$$

$$\text{subject to } k_{t+1} = k_t^\alpha - c_t \text{ and } \lim_{t \rightarrow \infty} k_t \geq 0$$

Start with $u_t = k_{t+1} = h_0 \cdot k_t^\alpha \Rightarrow c_t = (1 - h_0)k_t^\alpha$.

Next form:

$$\begin{aligned} J_0(k_0) &= \sum_{t=0}^{\infty} \beta^t \ln[(1 - h_0)k_t^\alpha] \\ &= \sum_{t=0}^{\infty} \beta^t \{\ln(1 - h_0) + \alpha \ln k_0\} \\ &= \frac{\ln(1 - h_0)}{1 - \beta} + \sum_{t=0}^{\infty} \alpha \beta^t \ln k_t \\ &= \frac{\ln(1 - h_0)}{1 - \beta} + \alpha [\ln k_0 + \beta \ln k_1 + \beta^2 \ln k_2 + \dots] \end{aligned}$$

But recall that:

$$k_{t+1} = h_0 \cdot k_t^\alpha \Rightarrow \ln k_{t+1} = \ln(h_0) + \alpha \ln k_t.$$

Therefore:

$$\begin{aligned} \ln k_1 &= \ln(h_0) + \alpha \ln k_0 \\ \ln k_2 &= \ln h_0 + \alpha \ln k_1 \\ &= \ln h_0 + \alpha [\ln(h_0) + \alpha \ln k_0] \\ &= (1 + \alpha) \ln h_0 + \alpha^2 \ln k_0 \end{aligned}$$

Pattern becomes:

$$\ln k_t = [1 + \alpha + \alpha^2 + \dots + \alpha^{t-1}] \ln h_0 + \alpha^t \ln k_0$$

Now recall:

$$\begin{aligned}
J_0(k_0) &= \frac{\ln(1-h_0)}{1-\beta} + \alpha[\ln k_0 + \beta \ln k_1 + \beta^2 \ln k_2 + \dots] \\
&= \frac{\ln(1-h_0)}{1-\beta} + \alpha \ln k_0 \\
&\quad + \alpha\beta[\ln(h_0) + \alpha \ln k_0] \\
&\quad + \alpha\beta^2[(1+\alpha)\ln h_0 + \alpha^2 \ln k_0] \\
&\quad + \alpha\beta^3[(1+\alpha+\alpha^2)\ln h_0 + \alpha^3 \ln k_0] + \dots
\end{aligned}$$

Therefore:

$$\begin{aligned}
J_0(k_0) &= \text{constant} + \alpha \ln k_0 + \alpha^2 \beta \ln k_0 + \alpha^3 \beta^2 \ln k_0 + \dots \\
&= \text{constant} + \alpha[1 + \alpha\beta + (\alpha\beta)^2 + \dots] \ln k_0 \\
&= \text{constant} + \frac{\alpha}{(1-\alpha\beta)} \ln k_0
\end{aligned}$$

Now denote the hypothetical value function as J_0 .

Bellman Equation is given by:

$$\begin{aligned}
V(k_t) &= \ln(k_t^\alpha - k_{t+1}) + \beta J_0(k_{t+1}) \\
&= \ln(k_t^\alpha - k_{t+1}) + \beta \times \text{constant} + \frac{\alpha\beta}{(1-\alpha\beta)} \ln k_{t+1}
\end{aligned}$$

Maximize with respect to k_{t+1}

First-order condition:

$$\begin{aligned}
\frac{-1}{k_t^\alpha - k_{t+1}} + \frac{\alpha\beta}{1-\alpha\beta} \frac{1}{k_{t+1}} &= 0 \\
\frac{1}{k_t^\alpha - k_{t+1}} &= \frac{\alpha\beta}{1-\alpha\beta} \frac{1}{k_{t+1}}
\end{aligned}$$

Solve for $k_{t+1}^* = \alpha\beta k_t \Rightarrow h_1 = \alpha\beta$ and $c_t = (1-h_1)k_t$

Iteration works in one step.

Value Function Iteration

We may also iterate on the value function. We start with an arbitrarily selected candidate value function. As one possibility, choose:

$$V(k_t) = v_0(k_t) = 0 \forall k_t$$

Now consider the problem:

$$\text{Max}_{u_t} \{u(c_t) + \beta v_0(k_t)\} = \{\ln(k_t^\alpha - u_t) + \beta \cdot 0\}$$

Trivially,

$$c_t^* = k_t^\alpha \text{ and } u_t^* = k_{t+1}^* = 0$$

The new value function becomes:

$$\begin{aligned}v_1(k_t) &= \ln(k_t^\alpha) + \beta \cdot 0 \\ &= \alpha \ln k_t\end{aligned}$$

New problem:

$$\text{Max}_{u_t} \{u(c_t) + \beta v_1(k_t)\} = \{\ln(k_t^\alpha - u_t) + \alpha\beta \ln u_t\}$$

First-order condition:

$$\begin{aligned}0 &= \frac{-1}{k_t^\alpha - u_t} + \frac{\alpha\beta}{u_t} \\ u_t &= \alpha\beta k_t^\alpha - \alpha\beta u_t\end{aligned}$$

Therefore:

$$u_t^* = k_{t+1}^* = \frac{\alpha\beta}{(1 + \alpha\beta)} k_t^\alpha \Rightarrow c_t^* = k_t^\alpha - u_t^*$$

$$c_t^* = \left(1 - \frac{\alpha\beta}{1 + \alpha\beta}\right) k_t^\alpha = \frac{k_t^\alpha}{(1 + \alpha\beta)}$$

The new value function becomes:

$$\begin{aligned}v_2(k_t) &= \ln\left(\frac{k_t^\alpha}{(1 + \alpha\beta)}\right) + \beta \cdot \alpha \ln k_{t+1}^* \\ &= \ln\left(\frac{k_t^\alpha}{(1 + \alpha\beta)}\right) + \alpha\beta \ln\left(\frac{\alpha\beta}{(1 + \alpha\beta)} k_t^\alpha\right) \\ &= \ln\left(\frac{1}{1 + \alpha\beta}\right) + \alpha \ln k_t + \alpha\beta \ln\left(\frac{\alpha\beta}{(1 + \alpha\beta)}\right) + \alpha^2 \beta \ln k_t\end{aligned}$$

Collecting terms:

$$v_2(k_t) = \ln\left(\frac{1}{1 + \alpha\beta}\right) + \alpha\beta \ln\left(\frac{\alpha\beta}{(1 + \alpha\beta)}\right) + \alpha(1 + \alpha\beta) \ln k_t$$

Next consider:

$$\text{Max}_{u_t} \left\{ \ln(k_t^\alpha - u_t) + \beta \cdot \left[\ln\left(\frac{1}{1 + \alpha\beta}\right) + \alpha\beta \ln\left(\frac{\alpha\beta}{(1 + \alpha\beta)}\right) + \alpha(1 + \alpha\beta) \ln u_t \right] \right\}$$

First-order condition:

$$\begin{aligned}0 &= \frac{-1}{k_t^\alpha - u_t} + \alpha\beta(1 + \alpha\beta) \frac{1}{u_t} \\ u_t &= \alpha\beta(1 + \alpha\beta) k_t^\alpha - \alpha\beta(1 + \alpha\beta) u_t \\ u_t^* &= k_{t+1}^* = \frac{\alpha\beta(1 + \alpha\beta)}{1 + \alpha\beta(1 + \alpha\beta)} k_t^\alpha\end{aligned}$$

We can also solve for:

$$\begin{aligned}
c_t^* &= k_t^\alpha - u_t^* \\
&= k_t^\alpha \left[\frac{1 + \alpha\beta(1 + \alpha\beta) - \alpha\beta(1 + \alpha\beta)}{1 + \alpha\beta(1 + \alpha\beta)} \right] \\
&= \frac{1}{1 + \alpha\beta(1 + \alpha\beta)} k_t^\alpha \\
&= \frac{1}{1 + \alpha\beta + (\alpha\beta)^2} k_t^\alpha
\end{aligned}$$

A pattern is emerging in which, in the limit:

$$\begin{aligned}
c_t^*(1 + \alpha\beta + (\alpha\beta)^2 + \dots) &= k_t^\alpha \\
\frac{c_t^*}{(1 - \alpha\beta)} &= k_t^\alpha
\end{aligned}$$

Therefore:

$$c_t^* = (1 - \alpha\beta)k_t^\alpha$$

Stochastic Problems

Consider the problem:

$$\text{Max}_{u_t} E_0 \left(\sum_{t=0}^{\infty} \beta^t r(x_t, u_t) \right)$$

$$\text{subject to: } x_{t+1} = g(x_t, u_t, \epsilon_{t+1}),$$

$$\text{where: } \epsilon_t \text{ is iid, with } \text{Prob}\{\epsilon_t \leq e\} = F(e), \forall t$$

At each t , x_t and ϵ_t are known.

But u_t must be chosen before the realization of ϵ_{t+1}

Solution to the stochastic problem is a contingency plan.

Choice of u_t should not be made until the realization of ϵ_t .

Classical procedures no longer apply.

The Classical solution jointly determines all of the u_t at $t = 0$.

Not very helpful for deciding on a contingency plan.

We first consider:

$$\text{Max}_{u_t} E_1 [r(x_1, u_1) + \beta r(x_2, u_2) + \dots]$$

Conjecture that the solution is $u_t = h(x_t)$.

Solution is an autonomous contingency rule.

If $h(\cdot)$ is known, we may compute:

$$E_1 V(x_1) = E_1 [r(x_1, h(x_1)) + \beta r(x_2, h(x_2)) + \dots]$$

$$\text{with } x_{t+1} = g(x_t, h(x_t), \epsilon_{t+1})$$

We again call $V(\cdot)$ the value function.

Next, we reconsider:

$$\text{Max}_{u_t} E_0 \left(\sum_{t=0}^{\infty} \beta^t r(x_t, u_t) \right)$$

Right-hand side may be rewritten as:

$$\begin{aligned} &= E_0[r(x_0, u_0) + \beta r(x_1, u_1) + \beta^2 r(x_2, u_2) + \dots] \\ &= E_0\{r(x_0, u_0) + \beta E_1[r(x_1, h(x_1)) + \beta r(x_2, h(x_2)) + \dots]\} \\ &= r(x_0, u_0) + \beta E_0\{E_1[r(x_1, h(x_1)) + \beta r(x_2, h(x_2)) + \dots]\} \\ &= r(x_0, u_0) + \beta E_0\{E_1[V(x_1)]\} = r(x_0, u_0) + \beta E_0[V(x_1)] \end{aligned}$$

Original problem may therefore be written as:

$$\text{Max}_{u_0} [r(x_0, u_0) + \beta E_0 V(x_1)] \text{ where } x_1 = g(x_0, u_0, \epsilon_1)$$

The Bellman equation is given by:

$$V(x) = \text{Max}_u r(x, u) + \beta E[V(g(x, u, \epsilon))|x]$$

$$\text{where: } E[V(g(x, u, \epsilon))|x] = \int V(g(x, u, \epsilon)) dF(\epsilon)$$

We may now iterate on:

$$V_{j+1}(x) = \text{Max}_u (r(x, u) + \beta E[V_j(g(x, u, \epsilon))|x])$$

Differentiating the RHS, we obtain:

$$\frac{\partial r(x, u)}{\partial u} + \beta E \left[\frac{\partial g}{\partial u}(x, u, \epsilon) V'(g(x, u, \epsilon)) | x \right] = 0$$

The value function also satisfies:

$$V'(x) = \frac{\partial r(x, h(x))}{\partial x} + \beta E \left[\frac{\partial g}{\partial x}(x, h(x), \epsilon) V'(g(x, h(x), \epsilon)) | x \right]$$

When $\frac{\partial g}{\partial x} = 0$, the formula for $V'(x)$ becomes:

$$V'(x) = \frac{\partial r(x, h(x))}{\partial x}$$

Combine $V'(x)$ and FOC to obtain the stochastic Euler equation:

$$\frac{\partial r(x_t, u_t)}{\partial u_t} + \beta E \left[\frac{\partial g(x_t, u_t, \epsilon_{t+1})}{\partial u_t} \frac{\partial r(x_{t+1}, u_{t+1})}{\partial x_{t+1}} \Big| x_t \right] = 0$$

Stochastic Guess and Verify

Consider the stochastic version of the Ramsey problem:

$$\text{Max}_{c_t} E_0 \left(\sum_{t=0}^{\infty} \beta^t \ln(c_t) \right)$$

subject to $k_{t+1} = \theta_t k_t^\alpha - c_t$ and $\lim_{t \rightarrow \infty} k_t \geq 0$

$$E_t[\ln(\theta_{t+1})] = 0$$

Guess that:

$$V(k_t, \theta_t) = \Omega + F \ln k_t + G \ln(\theta_t)$$

Recall that:

$$c_t = \theta_t k_t^\alpha - k_{t+1}$$

We may now write the maximization as:

$$\text{Max}_{k_{t+1}} \{ \ln(\theta_t k_t^\alpha - k_{t+1}) + \beta E_t[\Omega + F \ln k_{t+1} + G \ln(\theta_{t+1})] \}$$

First-order condition:

$$\begin{aligned} 0 &= \frac{\partial}{\partial k_{t+1}} \{ \ln(\theta_t k_t^\alpha - k_{t+1}) + \beta[\Omega + F \ln k_{t+1}] \} \\ &= \frac{-1}{\theta_t k_t^\alpha - k_{t+1}} + \frac{\beta F}{k_{t+1}} \\ k_{t+1} &= \beta F [\theta_t k_t^\alpha - k_{t+1}] \end{aligned}$$

Rearrange to obtain:

$$k_{t+1}^* = \frac{\beta F}{1 + \beta F} \theta_t k_t^\alpha$$

Next recall that:

$$\begin{aligned} c_t^* &= \theta_t k_t^\alpha - k_{t+1}^* \\ &= \theta_t k_t^\alpha - \frac{\beta F}{1 + \beta F} \theta_t k_t^\alpha \end{aligned}$$

Collecting terms:

$$c_t^* = \left[1 - \frac{\beta F}{1 + \beta F} \right] \theta_t k_t^\alpha = \frac{\theta_t k_t^\alpha}{1 + \beta F}$$

We next evaluate the Bellman equation at c_t^* and k_{t+1}^* to obtain:

$$\begin{aligned} V(k_t, \theta_t) &= \max \{ \ln c_t + \beta E_t V(k_{t+1}, \theta_{t+1}) \} \\ &= \ln c_t^* + \beta E_t [\Omega + F \ln k_{t+1}^* + G \ln(\theta_{t+1})] \\ &= \ln \left[\frac{\theta_t k_t^\alpha}{1 + \beta F} \right] + \beta \Omega + \beta F \ln \left[\frac{\beta F}{1 + \beta F} \theta_t k_t^\alpha \right] + \beta G \cdot 0 \end{aligned}$$

Therefore:

$$\begin{aligned} V(k_t, \theta_t) &= \ln(\theta_t) + \alpha \ln(k_t) - \ln(1 + \beta F) \\ &\quad + \beta \Omega + \beta F \ln \left(\frac{\beta F}{1 + \beta F} \right) + \beta F \ln(\theta_t) + \alpha \beta F \ln(k_t) \end{aligned}$$

Expand to:

$$V(k_t, \theta_t) = [\beta\Omega - \ln(1 + \beta F) + \beta F \ln(\beta F) - \beta F \ln(1 + \beta F)] \\ + (1 + \beta F) \ln(\theta_t) + \alpha(1 + \beta F) \ln(k_t)$$

Now match coefficients:

$$\Omega = \frac{\beta F \ln(\beta F) - (1 + \beta F) \ln(1 + \beta F)}{1 - \beta}$$

$$F = \alpha(1 + \beta F) \Rightarrow F = \frac{\alpha}{1 - \alpha\beta}$$

$$G = 1 + \beta F = \frac{1}{1 - \alpha\beta}$$

Finally:

$$k_{t+1} = \frac{\beta F}{1 + \beta F} \theta_t k_t^\alpha = \alpha \beta \theta_t k_t^\alpha$$

$$c_t = \theta_t k_t^\alpha - k_{t+1} = (1 - \alpha\beta) \theta_t k_t^\alpha$$

$$\Omega = \frac{1}{1 - \beta} \left\{ \frac{\alpha\beta}{(1 - \alpha\beta)} \ln(\alpha\beta) + \frac{\ln(1 - \alpha\beta)}{(1 - \alpha\beta)} \right\}$$

and:

$$V(k_t, \theta_t) = \Omega + \frac{\alpha \ln k_t + \ln(\theta_t)}{(1 - \alpha\beta)}$$